

Geometry of one-dimensional wave propagation

M. Kitano

Department of Electronics, Kyoto University

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Abstract

We investigate the geometrical features of one-dimensional wave propagation, whose dynamics is described by the $(2+1)$ -dimensional Lorentz group. We find many interesting geometrical ingredients such as spinorlike behavior of wave amplitudes, gauge transformations, Bloch-type equations, and Lorentz-group Berry phases. We also propose an optical experiment to verify these effects.

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I. INTRODUCTION

The Berry phases [1] produced by rotations have been most extensively studied for various physical systems. Another interesting class consists of Berry phases produced by Lorentz transformations. Chiao and Jordan [2] showed that Lorentz-group Berry phases could be observed as a change of phase of the electromagnetic field in squeezed states. Successive squeezing operations for either light or microwaves by degenerate parametric amplifiers induce a phase shift that can be interpreted geometrically. These kinds of experiments have drawn considerable interest because they can be viewed as the quantum optical realization of the Lorentz kinematics. [3,4]

Another optical manifestation of the Lorentz-group Berry's phase was proposed and experimentally verified [5]. It is shown that when one cycles light through a sequence of partially polarized states, the light acquires a geometrical phase.

It is well known that the wave propagation in one dimension (1D) can be described by the Lorentz-group dynamics, therefore, one can expect Lorentz-group Berry phases in wave systems. In this paper, we present Berry phases and related geometrical features seen in the 1D wave propagation in inhomogeneous media.

In Sec. II, from the 1D wave equation with quasi-periodic potential we derive a Schrödinger-like equation, which explicitly exhibits the Lorentz dynamics via the generators of $SL(2,R)$. The dynamical variables of the equation are the two quadrature wave amplitudes, which form a two-column state vector.

In Sec. III, a $SL(2,R)$ -Bloch equation is derived from the Schrödinger-like equation. The equation is very similar to the conventional $SU(2)$ -Bloch equation for the spin-1/2 except that the $SL(2,R)$ -Bloch vector moves on a conical surface not on a sphere. The similarity could be very useful for the geometrical understanding of Lorentz dynamics, especially because the $SU(2)$ -Bloch model has been successfully employed in various fields such as nuclear magnetic resonances, nonlinear optics, polarization optics, interferometry, and atomic physics, etc.

In Sec. IV, we discuss two-valuedness of the state vectors. A Bloch vector represents a pair of state vectors with opposite signs. When a Bloch vector circles around the apex of a cone, the corresponding state vector changes its sign. It is shown that the two-valuedness comes from a symmetry of the wave equation with respect to the translation of half wave-length.

Extending the above geometrical situation, we introduce in Sec. V a local gauge transformation associated with the deformation of space coordinate.

So far, we have assumed that the state vector is real because the potential function in the wave equation is real. It turns out, however, the extension to complex wave functions is very convenient, because a complex solution could represent two linearly independent real solutions at once. In Sec. VI, we derive a Bloch equation for the case of complex amplitudes. In this case, a Bloch vector corresponds to a set of state vectors that differ only in phase factors. The Bloch vector moves on the surface of hyperboloid. This is the arena where the Berry phase plays a role. In Sec. VII, we define the Berry phase for a cyclic evolution of the system.

Finally, we propose a feasible optical experiment where we can observe the Berry phase for 1D wave propagation.

II. 1D WAVE EQUATION AND $SL(2, \mathbb{R})$

Let us start with a one-dimensional wave equation (the Helmholtz equation) for a monochromatic wave $\Psi(x)e^{-i\omega t}$

$$\left\{ \frac{d^2}{dx^2} + k^2[1 + \epsilon(x)] \right\} \Psi(x) = 0, \quad (1)$$

where $k = k(\omega)$ is the wave number in free ($\epsilon = 0$) space.

We assume the spatial variation of the refractive index or the potential $\epsilon(x)$ has the following form:

$$\epsilon(x) = \epsilon_0(x) + 2\epsilon_c(x) \cos 2kx + 2\epsilon_s(x) \sin 2kx. \quad (2)$$

The spatial modulation at wave number $2k$ strongly modifies the propagation of the wave with wave number k owing to the Bragg effect. The DC component ϵ_0 also has substantial influences through the Bragg resonance condition.

We represent the wave $\Psi(x)$ with mean wave number k as

$$\Psi(x) = A(x) \cos kx + B(x) \sin kx, \quad (3)$$

where $A(x)$ and $B(x)$ are slowly varying envelope functions. These envelopes are normally considered to be real functions, since $\epsilon(x)$ in Eq. (1) is real. However, the extension to complex functions is sometimes very useful as will be discussed in Sec. VI.

Substitution of Eqs. (2) and (3) into Eq. (1) gives

$$\frac{d}{dx} \begin{bmatrix} A \\ B \end{bmatrix} = \frac{k}{2} \begin{bmatrix} \epsilon_s & -\epsilon_c + \epsilon_0 \\ -\epsilon_c - \epsilon_0 & -\epsilon_s \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix}, \quad (4)$$

which can be rewritten in a Schrödinger-like form

$$ik^{-1} \frac{d}{dx} |\psi\rangle = -\boldsymbol{\epsilon}(x) \cdot \mathbf{K} |\psi\rangle. \quad (5)$$

with the column vector $|\psi\rangle = (A, B)^T$. Here we introduced $\boldsymbol{\epsilon}(x) = (-\epsilon_s, \epsilon_c, \epsilon_0) = (\epsilon_1, \epsilon_2, \epsilon_3)$, and $\mathbf{K} = (K_1, K_2, J_3)$, with

$$K_1 = i\sigma_3/2, \quad K_2 = i\sigma_1/2, \quad J_3 = \sigma_2/2, \quad (6)$$

where $\sigma_i (i = 1, 2, 3)$ are the Pauli's spin matrices.

We have assumed that $A(x)$ and $B(x)$ do not change appreciably over distances of the order of k^{-1} (slowly-varying-envelope approximation) and neglected the terms with wavelength $\pm 3k$ (secular-term approximation).

The matrices (6) are the generators of $SL(2, \mathbb{R})$, the two dimensional real unimodular group, and satisfy the commutation relations

$$[K_1, K_2] = -iJ_3, \quad [K_2, J_3] = iK_1, \quad [J_3, K_1] = iK_2. \quad (7)$$

The (A, B) plane is squeezed in one direction and stretched in the orthogonal direction by the generators K_1 or K_2 , and rotated by J_3 .

The group $SL(2, \mathbb{R})$ has the close connection (locally isomorphic) to the (2+1)-dimensional Lorentz group $SO(2, 1)$ as does the group $SU(1, 1)$. Instead of Eq. (3), if we use a representation

$$\Psi(x) = \mathcal{A}(x)e^{-ikx} + \mathcal{B}(x)e^{ikx}, \quad (8)$$

then we have the $SU(1, 1)$ -Schrödinger equation with $K'_1 = i\sigma_1/2$, $K'_2 = -i\sigma_2/2$, $J'_3 = \sigma_3/2$, which satisfy the same commutation relations as Eq. (7). In the following discussion, we mostly use $SL(2, \mathbb{R})$ rather than $SU(1, 1)$.

III. $SL(2, \mathbb{R})$ -BLOCH EQUATION – REAL AMPLITUDE CASE

Equation (5) has a form similar to the Schrödinger equation for the spin-1/2 (\mathbf{J}) in time varying magnetic fields $\mathbf{B}(t)$; $i\hbar(d/dt)|\psi\rangle = -\mathbf{B}(t) \cdot \mathbf{J}|\psi\rangle$. The underlying group for the spin-1/2 dynamics is $SU(2)$, which is the covering group of the three dimensional rotation group, $SO(3)$. The Bloch equation derived from the spin-1/2 Schrödinger equation apparently reflects the structure of those groups; the Bloch vector moves on a sphere, and the Berry phase for spin-1/2 can be related to the surface area of the sphere.

In order to see the geometrical structure of $SL(2, \mathbb{R})$ -dynamics, let us derive the corresponding Bloch equation. (A more detailed derivation will be given in Sec. VI. See also Ref. [6].)

First we define the 2×2 density matrix ρ as

$$\rho = 2i|\psi\rangle\langle\psi|J_3 = i\mathbf{s} \cdot \mathbf{K}, \quad (9)$$

where $\langle\psi|$ represents the row vector (A, B) , and $\mathbf{s} = (s_1, s_2, s_3)$ the Bloch vector. We note,

$$\mathbf{s} = (2AB, -A^2 + B^2, A^2 + B^2). \quad (10)$$

The equation of motion for ρ can be obtained from Eq. (5) as

$$ik^{-1} \frac{d\rho}{dx} = [-\boldsymbol{\epsilon} \cdot \mathbf{K}, \rho]. \quad (11)$$

Using the commutation relations (7), we have the equation of motion for \mathbf{s}

$$k^{-1} \frac{d\mathbf{s}}{dt} = \boldsymbol{\epsilon} \tilde{\times} \mathbf{s}, \quad (12)$$

where the SU(1,1) vector product defined as

$$\mathbf{a} \tilde{\times} \mathbf{b} = (a_2 b_3 - a_3 b_2, a_3 b_1 - a_1 b_3, -a_1 b_2 + a_2 b_1). \quad (13)$$

for two vectors, $\mathbf{a} = (a_1, a_2, a_3)$ and $\mathbf{b} = (b_1, b_2, b_3)$. We also define the SU(1,1) scalar product

$$\mathbf{a} \tilde{\cdot} \mathbf{b} = a_1 b_1 + a_2 b_2 - a_3 b_3. \quad (14)$$

Then from Eq. (10), we have

$$\mathbf{s} \tilde{\cdot} \mathbf{s} = 0, \quad s_3 \geq 0, \quad (15)$$

which means the Bloch vector \mathbf{s} moves on the surface of the (upper) cone depicted in Fig. 1.

When $\boldsymbol{\epsilon}(x)$ is constant, trajectories for \mathbf{s} are very simple; the vector \mathbf{s} lies in a plane that is orthogonal to the vector $\tilde{\boldsymbol{\epsilon}} = (\epsilon_1, \epsilon_2, -\epsilon_3)$, because

$$\frac{d\mathbf{s}}{dx} \tilde{\cdot} \boldsymbol{\epsilon} = \frac{d\mathbf{s}}{dx} \cdot \tilde{\boldsymbol{\epsilon}} = 0. \quad (16)$$

A trajectory, which is the intersection of a plane and the cone could be an ellipse, a parabola, or a hyperbola according as ϵ_3^2 is greater than, equal to, or less than $\epsilon_1^2 + \epsilon_2^2$. The elliptical, bound trajectories correspond to the propagating waves in the conduction bands and the hyperbolic, unbound trajectories correspond to the evanescent waves in the forbidden bands.

Owing to the geometrical simplicity and the similarity to the conventional Bloch equation, the SL(2,R)-Bloch equation could be very useful.

IV. TWO-VALUEDNESS

In this section, we study a subtler geometrical feature of SL(2,R)-Bloch equation. We note the correspondence between (A, B) and \mathbf{s} given by Eq. (10) is not one to one but two to one; a single vector \mathbf{s} represents two state vectors with opposite signs: (A, B) and $(-A, -B)$.

At first sight, these two state vectors may seem to represent two distinct physical situations. Within the framework of the present approximation (slowly varying envelopes), however, the two situations are virtually identical. Figure 2 represents the local pictures of waves with opposite polarities (real lines). A potential with period $\sim \pi k^{-1}$ is also shown (dashed lines). We note the dispositions of the waves relative to the potential are the same and, therefore, the waves would evolve identically.

This degeneracy comes from the fact that the potential (2) is invariant under the translation $x \rightarrow x + n\pi k^{-1}$ (n : integer), as far as the variation of $\epsilon(x)$ over the distance $n\pi k^{-1}$ can be neglected;

$$\epsilon(x + n\pi k^{-1}) \sim \epsilon(x). \quad (17)$$

On the other hand, from Eq. (3), we see that the translation induces $(A, B) \rightarrow (-1)^n(A, B)$.

In order to see the geometrical structure of the two-valued representation, we can make a cone from the (A, B) plane as shown in Fig. 3. The (A, B) plane is cut along a line from the origin ($+A$ axis in this example) and is wrapped to make a twofold cone with apex angle of 60 degrees. When the vector \mathbf{s} on the cone encircles a closed curve around the apex, we see that the corresponding (A, B) gains a factor $(-1)^n$, where n is the winding number of the curve.

Even though, two vectors (A, B) and $(-A, -B)$ represent (almost) the same physical situation, we can conveniently detect the minus sign by interferometric methods, as that for spin 1/2 rotated by 2π [7]. (The two cases have good analogy, but it is only for the latter case that interference experiments are absolutely required and even in principle there is no other way to detect the minus sign.)

Figure 4 shows an example of interferometry. We have two trajectories both of which start from $(A, B) = (1, 0)$ at $x = 0$. One evolves with a constant ϵ and the other with $-\epsilon$. After some evolution, they reach conjugate points in the (A, B) plane. Looking at the corresponding wave forms [Fig. 4(b)], we notice that the phase shifts accumulate to make signs opposite.

This situation reminds us of the sign change of a spinor rotated by 2π , the Aharonov-Bohm effect with an infinite solenoid, the sign change around the degeneracy of the eigenstates of real-Hamiltonian systems [8,9], and the (relative) configuration space of two identical particles in two-dimensional space [10]. In terms of the second analogy, the topological magnetic flux of $\pi\hbar c/e$ is required to account for the sign change or the phase shift of π . The amount of flux is consistent with the (singular) curvature at the cone apex or the apex angle.

Mathematically speaking, $SL(2, R)$ is a two-valued representation of the (2+1)-dimensional Lorentz group, $SO(2, 1)$, as $SU(2)$ is for the three-dimensional rotation group, $SO(3)$. It is very interesting that the two-valued representation which is believed peculiar to the quantum regime manifests itself in the classical context.

It should be noted that the cone introduced here and that for the Bloch vector discussed in the previous section have different apex angles and different parametrization:

$$\bar{\mathbf{s}} = (s_1, s_2, \sqrt{3}s_3)/2\sqrt{s_3}, \quad (18)$$

where $\bar{\mathbf{s}}$ is a vector in Fig. 3.

V. GAUGE TRANSFORMATION

In order to generalize the discussion in the previous section, we introduce a (local) gauge transformation. We conveniently use the $SU(1, 1)$ amplitudes [see Eq. (8)] \mathcal{A} and \mathcal{E} :

$$\mathcal{A} = (A + iB)/2, \quad \mathcal{E} = \epsilon_c + i\epsilon_s. \quad (19)$$

With this notation, the Schrödinger equation (5) can be represented in a scalar form as

$$2ik^{-1} \frac{d}{dx} \mathcal{A} = \mathcal{E} \mathcal{A}^* + \epsilon_0 \mathcal{A}, \quad (20)$$

where \mathcal{A}^* stands for the complex conjugate of \mathcal{A} .

Here we consider a space coordinate x' which is slightly deviated from x as

$$x' = x - \xi(x). \quad (21)$$

We assume the deviation ξ is small enough to assure $\mathcal{A}(x - \xi) \sim \mathcal{A}(x)$, $\mathcal{E}(x - \xi) \sim \mathcal{E}(x)$, and $\xi(x - \xi) \sim \xi(x)$ for any x . In the x' coordinate, \mathcal{A}' and \mathcal{E}' are defined as

$$\mathcal{A}' = \mathcal{A} e^{-ik\xi}, \quad \mathcal{E}' = \mathcal{E} e^{-2ik\xi} \quad (22)$$

respectively, and the equation of motion transforms as

$$2ik^{-1} \frac{d}{dx'} \mathcal{A}' = \mathcal{E}' \mathcal{A}'^* + \left[\epsilon_0 + 2 \frac{d\xi}{dx'} \right] \mathcal{A}'. \quad (23)$$

Here we have an extra term $2d\xi/dx'$ which accounts for the gauge transformation. This term can be interpreted as a gauge field.

In Eqs. (2) and (3), in order to define ϵ , A , and B , we needed a long yardstick accurately graduated in $2\pi k^{-1}$. However, with the help of the above equations, we can compare the wave amplitudes for two observers whose rulers are not necessarily accurate in a long span.

We note that the discussion in the previous section can be reproduced by considering the case of constant deviation $\xi(x) = n\pi k^{-1}$, which yields $\mathcal{A}' = -\mathcal{A}$, $\mathcal{E}' = \mathcal{E}$, and $d\xi/dx' = 0$. We consider two coordinate systems x and x' shifted by $n\pi k^{-1}$, and a third coordinate system $x'' = x + \xi(x)$, with $\xi(x) = 0$ for $x < x_1$ and $\xi(x) = n\pi k^{-1}$ for $x > x_2$; in the interval of $x_1 < x < x_2$, x'' smoothly connects x and x' . The integration of the gauge field

$$l = \int_{x_1}^{x_2} 2 \frac{d\xi(x)}{dx} dx = 2n\pi k^{-1}, \quad (24)$$

which is independent of the local behavior of ξ , amount to the sign factor $\exp(-inkl/2) = (-1)^n$ between (A, B) and (A', B') .

VI. SL(2,R) BLOCH EQUATION — COMPLEX AMPLITUDE CASE

From now on let us consider $|\psi\rangle = (\alpha, \beta)^T$ as complex amplitudes. Before proceeding, physical meaning of complex amplitudes should be clarified. At first sight of Eq. (1), which has real coefficients, no complex amplitudes seems required. In fact, if we decompose $|\psi\rangle$ into real and imaginary parts

$$|\psi\rangle = |\psi'\rangle + i|\psi''\rangle, \quad (25)$$

then each of $|\psi'\rangle$ and $|\psi''\rangle$ is a real solution to Eq. (5). Therefore, a complex solution could represent two independent real solutions. The independence is assured by $\alpha'\beta'' - \alpha''\beta' \neq 0$, where $|\psi'\rangle = (\alpha', \beta')^T$ and $|\psi''\rangle = (\alpha'', \beta'')^T$. A complex solution is convenient in the sense that any real solutions can be represented as $\text{Re}(z|\psi\rangle)$ with a complex number z .

Starting from the SL(2, R)-Schrödinger equation (5) with complex $|\psi\rangle$:

$$ik^{-1} \frac{d}{dx} |\psi\rangle = N(x) |\psi\rangle, \quad (26)$$

$$N(x) = \epsilon_1 K_1 + \epsilon_2 K_2 + \epsilon_3 J_3, \quad (27)$$

let us derive the corresponding Bloch-like equation. The adjoint equation [11] is

$$ik^{-1} \frac{d}{dx} |\varphi\rangle = N^\dagger(x) |\varphi\rangle, \quad (28)$$

$$N^\dagger(x) = -\epsilon_1 K_1 - \epsilon_2 K_2 + \epsilon_3 J_3, \quad (29)$$

or equivalently,

$$-ik^{-1} \frac{d}{dx} \langle\varphi| = \langle\varphi| N(x). \quad (30)$$

In our case, N and N^\dagger are related via

$$N^\dagger = RNR^{-1}, \quad (31)$$

where $R = -R^{-1} = \exp(i\pi J_3) = 2iJ_3$. With use of this relation, we can rewrite the adjoint equation (28) as

$$ik^{-1} \frac{d}{dx} R|\varphi\rangle = N(x)R|\varphi\rangle. \quad (32)$$

and find that $R|\varphi\rangle$ and $|\psi\rangle$ obey the same equation. Hence, if $R|\varphi(0)\rangle = |\psi(0)\rangle$, then $R|\varphi(x)\rangle = |\psi(x)\rangle$ for any x .

Now we introduce the density operator as

$$\rho = |\psi\rangle\langle\varphi| = |\psi\rangle\langle\psi|R, \quad (33)$$

which follows the evolution equation

$$ik^{-1} \frac{d}{dx} \rho = [N, \rho]. \quad (34)$$

The matrix representation of ρ is given as follows:

$$\rho = \begin{bmatrix} -\alpha\beta^* & |\alpha|^2 \\ -|\beta|^2 & \alpha^*\beta \end{bmatrix}. \quad (35)$$

It can be parametrized as

$$\rho = i(s_0 I/2 + s_1 K_1 + s_2 K_2 + s_3 J_3), \quad (36)$$

where

$$\begin{aligned} s_0 &= (\alpha^*\beta - \alpha\beta^*)/i, \\ s_1 &= \alpha^*\beta + \alpha\beta^*, \\ s_2 &= -|\alpha|^2 + |\beta|^2, \\ s_3 &= |\alpha|^2 + |\beta|^2. \end{aligned} \quad (37)$$

Substitution of (27) and (36) into (34) gives the equation of motion for $\mathbf{s} = (s_1, s_2, s_3)$:

$$k^{-1} \frac{d\mathbf{s}}{dx} = \boldsymbol{\epsilon} \tilde{\times} \mathbf{s}, \quad (38)$$

which resembles to the Bloch equation, except for the use of the SU(1,1) vector product.

We note that s_0 is a constant of motion and that the relation

$$\mathbf{s} \cdot \mathbf{s} = -s_0^2 \quad (39)$$

holds.

In the case of $s_0 = 0$, the vector \mathbf{s} moves on the surface of a cone in the (s_1, s_2, s_3) space, as in Sec. III; $s_0 = 0$ implies real amplitudes because α and β share the same phase, which can be eliminated.

In the case of $s_0 \neq 0$, \mathbf{s} moves on the surface of a two-sheet hyperboloid, as shown in Fig. 5. Without loss of generality, we normalize the state vectors as $s_0 = 1$.

VII. GEOMETRICAL PHASE

In the case of real amplitudes, a density matrix represents two states. On the other hand, in the case of complex amplitudes, a density matrix ρ represents an infinite number of state vectors. For example, the state $|\psi'\rangle = e^{-i\phi K_s}|\psi\rangle$, $|\varphi'\rangle = e^{i\phi K_s}|\varphi\rangle$ derived from $|\psi\rangle$ and $|\varphi\rangle$ with $K_s = \mathbf{s} \cdot \mathbf{K}$ yield the same density matrix;

$$\rho' = |\psi'\rangle\langle\varphi'| = e^{-i\phi K_s}|\psi\rangle\langle\varphi|e^{i\phi K_s} = \rho, \quad (40)$$

since K_s and $\rho = |\psi\rangle\langle\varphi| = i(s_0/2 + K_s)$ commute. In other words, a density matrix or a Bloch vector corresponds to an equivalence class of states: $\{e^{-i\phi K_s}|\psi\rangle \mid -2\pi \leq \phi < 2\pi\}$, or a ray.

Now we have a projective structure in which we can introduce the Aharonov-Anandan connection [12], thereby we can derive the dynamical phase and the geometrical phase associated with a cycle of evolution.

The equivalence class introduced above can be represented more conveniently by using a decomposition of the group element of $SL(2, \mathbb{R})$:

$$g = e^{-i\mu J_3} e^{-i\nu K_1} e^{-i\phi J_3}. \quad (41)$$

An arbitrary state $|\psi\rangle$ can be obtained from $|\psi_0\rangle = 2^{-1/2}(1, i)^T$, which belongs to a ray $\mathbf{s} = (0, 0, 1)$ as

$$|\psi\rangle = g|\psi_0\rangle, \quad \langle\varphi| = \langle\varphi_0|g^{-1}, \quad (42)$$

where $|\varphi_0\rangle = R^{-1}|\psi_0\rangle$. The density matrix for this state is

$$\rho = |\psi\rangle\langle\varphi| = e^{-i\mu J_3} e^{-i\nu K_1} |\psi_0\rangle\langle\varphi_0| e^{i\nu K_1} e^{i\mu J_3}, \quad (43)$$

which does not contain the parameter ϕ .

Now we see that all the states in a ray can be derived by applying a group action to the states $|\psi_\phi\rangle = e^{-i\phi J_3}|\psi_0\rangle$, whose real and imaginary parts are given as

$$|\psi'_\phi\rangle = \begin{bmatrix} \cos \phi/2 \\ \sin \phi/2 \end{bmatrix}, \quad |\psi''_\phi\rangle = \begin{bmatrix} -\sin \phi/2 \\ \cos \phi/2 \end{bmatrix}. \quad (44)$$

Thus the element in a ray can be parametrized by ϕ .

Reflecting the two-valuedness discussed in Sec. IV, the states with ϕ and $\phi + 2\pi$ in a ray have opposite signs.

Let us consider a cyclic evolution in which a state $|\psi(0)\rangle$ evolves and returns to a state $|\psi(L)\rangle = \exp(i\Phi)|\psi(0)\rangle$, which belongs to the same ray, i.e., $\rho(0) = \rho(L)$. The phase difference Φ is composed of a dynamical phase ϕ_D and a geometrical phase ϕ_G .

The geometrical phase ϕ_G or the Berry phase for this system is given as [5,13]

$$\phi_G = \int_S s_3^{-1} ds_1 \wedge ds_2, \quad (45)$$

where S is the area enclosed by the path. The integrand is an invariant two form under the group action. It should be noted that this two form is different from that for the surface curvature of the hyperboloid, $(2s_3^2 - 1)^{-2} ds_1 \wedge ds_2$, or that for the surface area of the hyperboloid, $(2 - s_3^{-2})^{1/2} ds_1 \wedge ds_2$. In the $SU(2)$ case, all of the three quantities have the same form incidentally.

VIII. CONCLUSIONS

In conclusion, we have explored geometrical features of 1D wave propagation. Underlying group of this problem is the (2+1)-dimensional Lorentz group. The geometrical approach

would be very helpful for intuitive understanding of various wave phenomena. It is also applicable to other systems which are governed by the Lorentz dynamics.

Finally we would like to propose an experiment to observe the Berry phase and other geometrical phenomena for the 1D wave propagation. In Fig. 6, an optical system is presented. We have a medium whose distribution of refractive index $\epsilon(x)$ can be controlled externally. It is possible to write a holographic grating in optical fibers or in some nonlinear media. The light propagated through the medium is reflected back with perfect mirror M . Thus we can prepare a state corresponding to $\mathbf{s}(0) = (0, 0, 1)$ on the mirror side ($x = 0$). By adjusting the mirror position, we can “tune” the phase ϕ_0 of the initial state as $|\psi(0)\rangle = (\cos \phi_0/2, \sin \phi_0/2)^T$ and hence we can map out the complex $|\psi\rangle$ via Eq. (44). If we set up $\epsilon(x)$ so that the evolution be cyclic, then the state on the other side ($x = L$) should be $|\psi(L)\rangle = (\cos \phi_L/2, \sin \phi_L/2)^T$. For a cyclic evolution, $\Phi = \phi_L - \phi_0$ is independent of ϕ_0 . With the Mach-Zehnder interferometer we can measure the difference $\Phi = \phi_G + \phi_D$.

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FIGURES

FIG. 1. Bloch vector \mathbf{s} (for real amplitudes) on the conic surface: $s_1^2 + s_2^2 - s_3^2 = 0$

FIG. 2. Waves with opposite polarities (real lines) have the same phase relationship with the half-periodic potential (dashed line).

FIG. 3. In order to identify (A, B) and $(-A, -B)$, which represent physically the same state, we make a twofold cone from the (A, B) plane by making a cut from the origin and wrapping.

FIG. 4. Interferometric detection of two-valuedness of wave amplitudes. (a) Two trajectories starting off from $(A, B) = (1, 0)$ at $x = 0$ evolved by $\epsilon = \pi(-2, 1, 3)/400$ (real line), and by $-\epsilon$ (dashed line), respectively, and reach conjugate points at $x = 100k^{-1}$. (b) Corresponding wave forms.

FIG. 5. Bloch vector \mathbf{s} (for complex amplitudes) on the hyperboloid: $s_1^2 + s_2^2 - s_3^2 = -1$

FIG. 6. Proposed experimental setup for measuring the Berry phase for a 1D wave system.

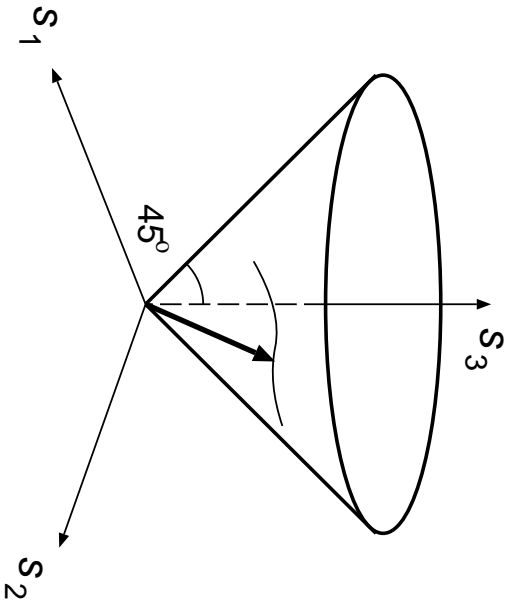
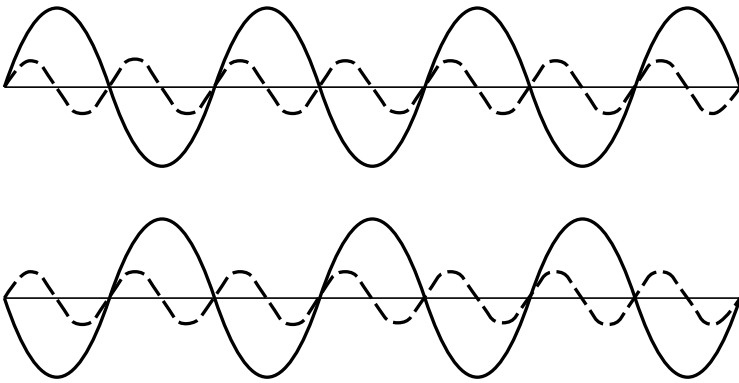
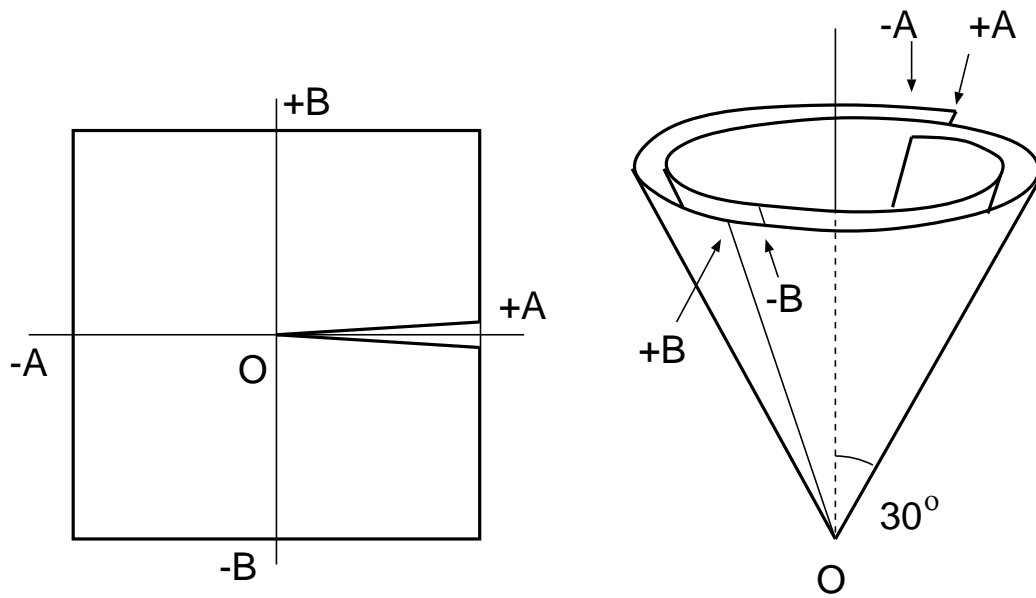
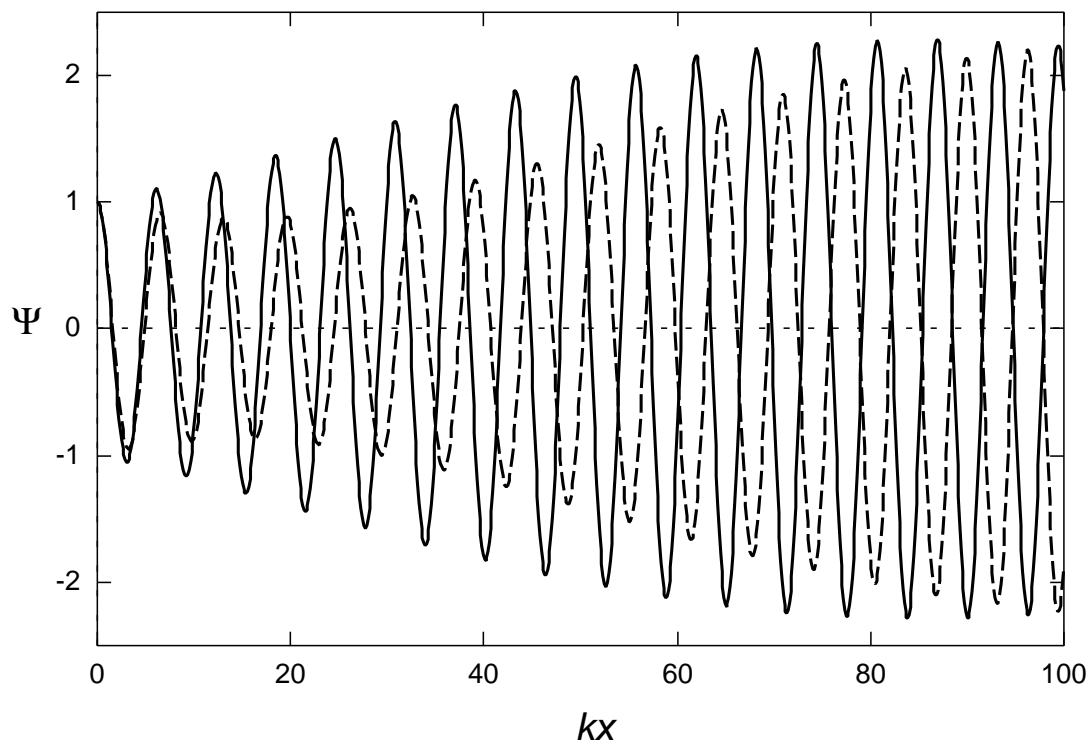
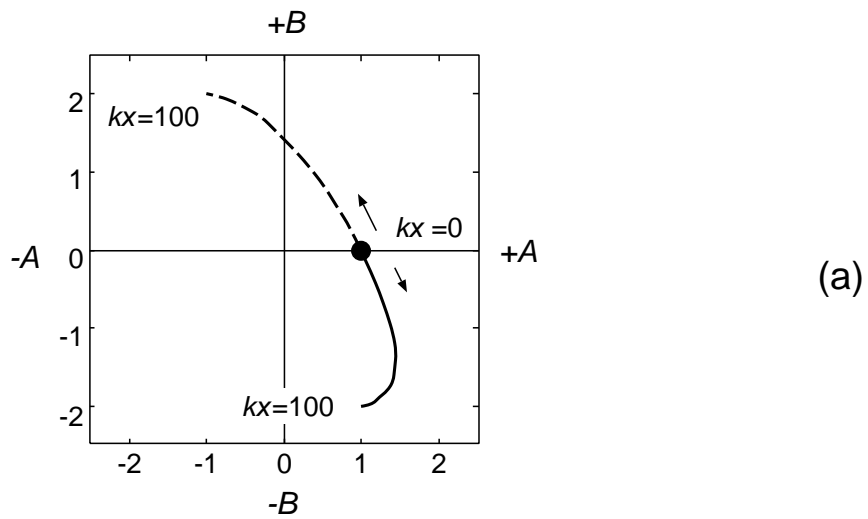


Figure. 1 *M. Kitano* Phys. Rev. A







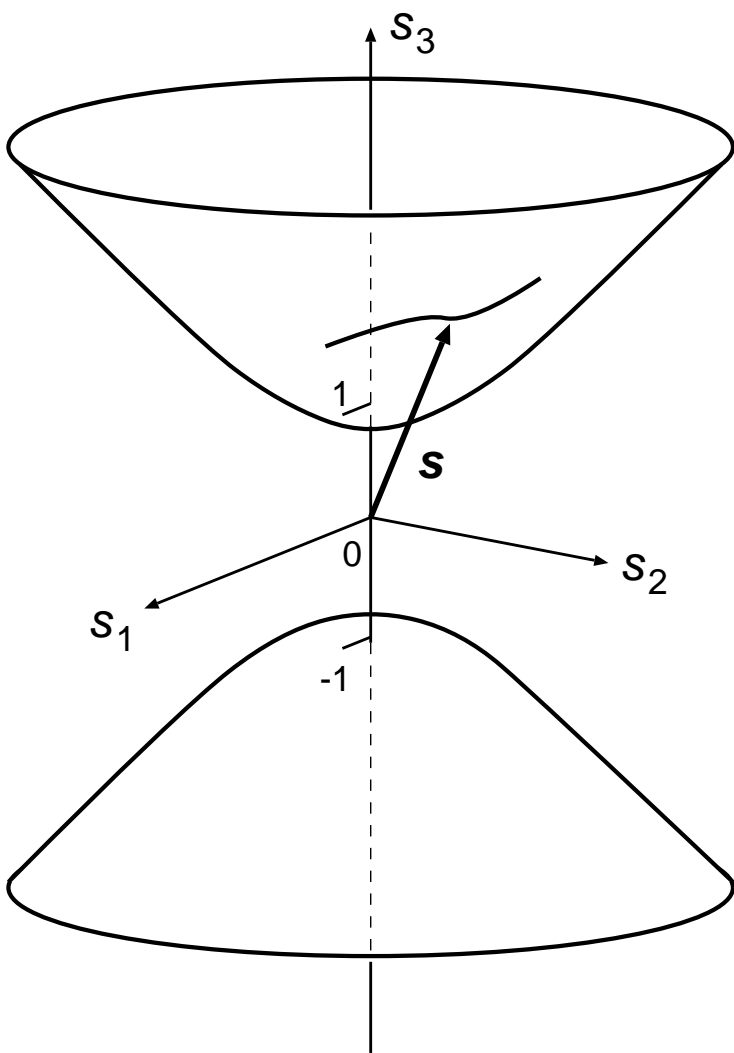


Figure. 5 *M. Kitano* Phys. Rev. A

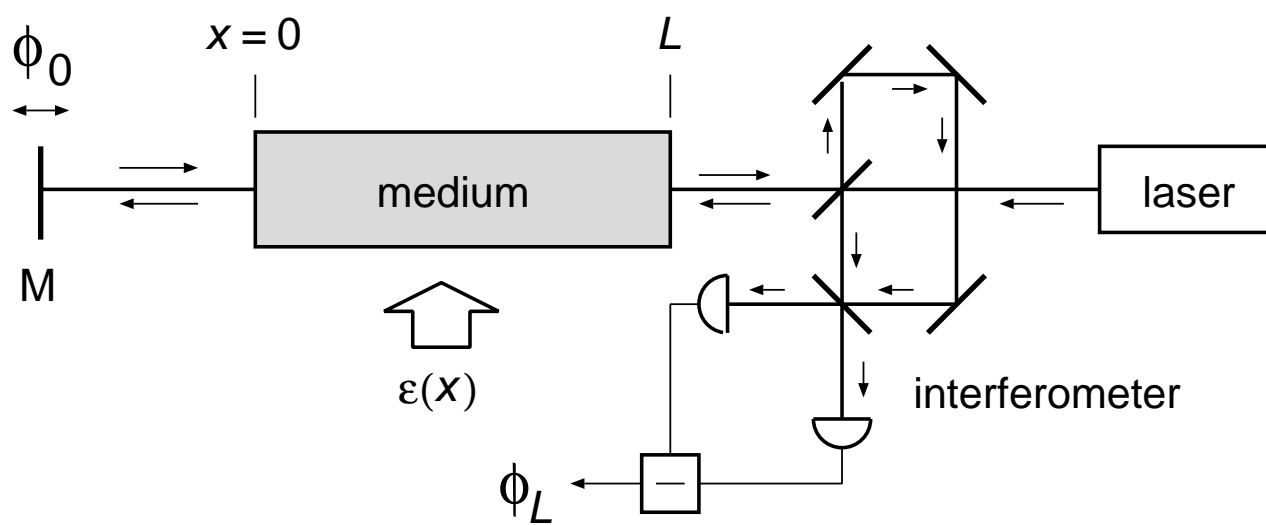


Figure. 6 *M. Kitano* Phys. Rev. A